

# A mixed finite element method with mass lumping for wave propagation

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## Acoustic wave equation

$$\begin{aligned}\partial_t u + \nabla p &= 0 && \text{in } \Omega \times (0, T), \\ \partial_t p + \operatorname{div} u &= 0 && \text{in } \Omega \times (0, T), \\ p &= 0 && \text{on } \partial\Omega \times (0, T).\end{aligned}$$

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### Remark (Existence and uniqueness)

Existence and uniqueness of a solution

$$(u, p) \in C([0, T], H(\operatorname{div}, \Omega) \times H_0^1(\Omega)) \cap C^1([0, T], L^2(\Omega)^2 \times L^2(\Omega))$$

for suitable initial and right hand side data follows from the semigroup theory.

## Variational formulation

$$\begin{aligned}\partial_t u + \nabla p &= 0 && \text{in } \Omega \times (0, T), \\ \partial_t p + \operatorname{div} u &= 0 && \text{in } \Omega \times (0, T), \\ p &= 0 && \text{on } \partial\Omega \times (0, T).\end{aligned}$$

### Variational characterization

$$(\partial_t u(t), v) - (p(t), \operatorname{div} v) = 0 \quad \forall v \in H(\operatorname{div}, \Omega)$$

$$(\partial_t p(t), q) + (\operatorname{div} u(t), q) = 0 \quad \forall q \in L^2(\Omega)$$

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### Remark

Each classical solution satisfies the variational characterization.

### Remark

The spaces corresponding to the weak formulation are  $L^2(\Omega)$  for  $p$  and  $H(\operatorname{div}, \Omega)$  for  $u$ .

## Discrete spaces

$$V_h = \text{BDM}_1 := \mathbf{P}_1^2(\mathcal{T}_h) \cap H(\text{div}, \Omega) \quad Q_h = \mathbf{P}_0 := \mathbf{P}_0(\mathcal{T}_h) \quad \text{div } V_h = Q_h$$

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Projection operators  $\rho_h : H^1(\mathcal{T}_h) \cap H(\text{div}, \Omega) \rightarrow V_h$  and  $\pi_h^0 : L^2(\Omega) \rightarrow Q_h$

$$\text{div } \rho_h \mathbf{v} = \pi_h^0 \text{div } \mathbf{v}$$

$$\|\mathbf{u} - \rho_h \mathbf{u}\|_{L^2(\Omega)} \leq Ch^2 |u|_{2,\Omega},$$

$$\|p - \pi_h^0 p\|_{L^2(\Omega)} \leq Ch |p|_{1,\Omega}.$$

## Discrete spaces

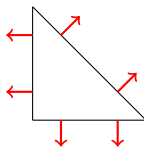
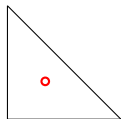
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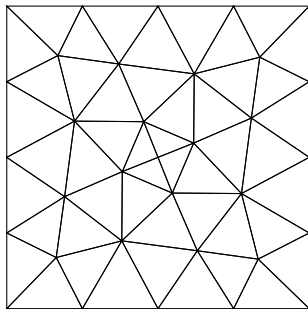
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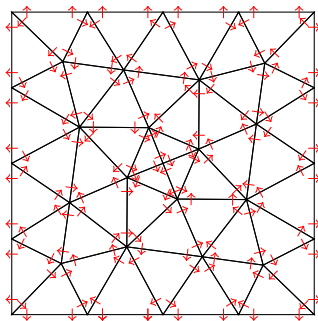
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# Semi-discretization

## Problem

For  $(u_h(0), p_h(0)) = (\rho_h u_0, \pi_h^0 p_0)$  and all  $t > 0$  find  $(u_h(t), p_h(t)) \in V_h \times Q_h$  such that

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## Theorem (Error estimate for the semi-discretization)

Let  $V_h = BDM_1$ ,  $Q_h = P_0$ . Then if  $(u, p)$  sufficiently smooth

$$\|u(t) - u_h(t)\|_{L^2(\Omega)} + \|p(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u, p)h.$$

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## Theorem (Post-processing for the pressure)

For  $(u, p)$  sufficiently smooth, we have

$$\|p(t) - \tilde{p}_h(t)\|_{L^2(\Omega)} \leq C(p, u) h^2$$

## Motivation for new method

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$$M\dot{\mathbf{u}}_h + B\mathbf{p}_h = 0$$

$$D\dot{\mathbf{p}}_h - B^\top \mathbf{u}_h = 0$$



## Motivation for new method

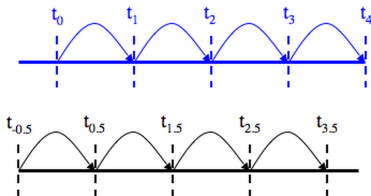
$$M \frac{\mathbf{u}_h^{n+1/2} - \mathbf{u}_h^{n-1/2}}{\tau} + B \mathbf{p}_h^n = 0$$
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Compute  $(\mathbf{u}_h^{n+1/2}, \mathbf{p}_h^{n+1})$  from  $(\mathbf{u}_h^{n-1/2}, \mathbf{p}_h^n)$ .

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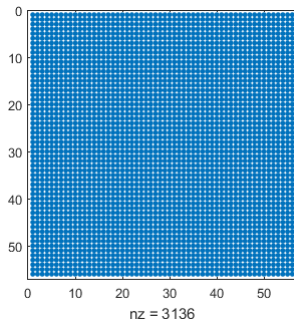
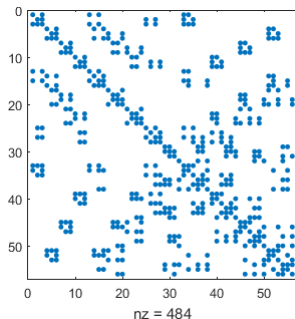
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Problem : Structure of matrix  $M$



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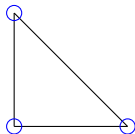
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$$(u_h, v_h)_h := \frac{|T|}{3} \sum_{i=1}^3 u_h(r_i) v_h(r_i)$$

where  $r_i$  represent the edges of the element.

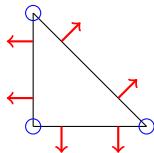


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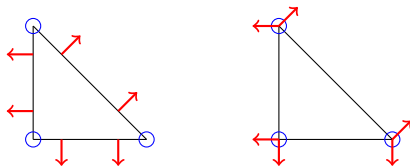


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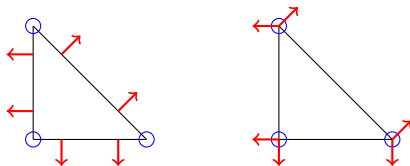


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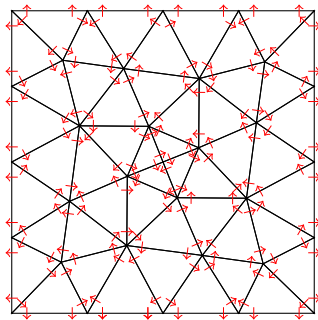
Norm equivalence

$$\frac{1}{2} \|v_h\|_{h,\Omega} \leq \|v_h\|_{L^2(\Omega)} \leq \|v_h\|_{h,\Omega}, \quad \forall v_h \in V_h.$$



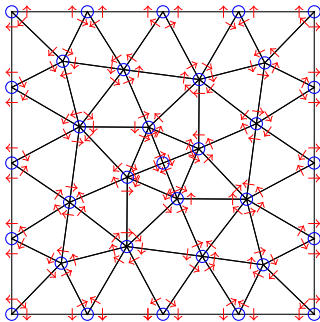
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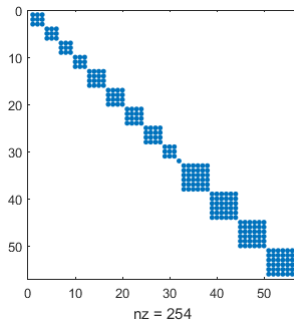
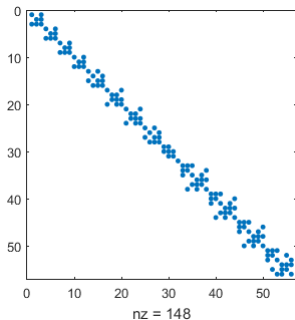
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What do we lose ? Let's take a look at what the numerical tests have to say...

$$\|\tilde{\pi}_h^0 u(t) - u_h(t)\|_{L^2(\Omega)} \leq Ch \qquad \|\pi_h^0 p(t) - p_h(t)\|_{L^2(\Omega)} \leq Ch^2.$$

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WHY ?

## Motivation for new method

### Problem

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### Lemma (Discrete energy estimate)

Let  $(u_h, p_h)$  denote the solution of the system above. Then

$$\begin{aligned}\|u_h(t)\|_{L^2(\Omega)} + \|p_h(t)\|_{L^2(\Omega)} \\ \lesssim \|u_h(0)\|_{L^2(\Omega)} + \|p_h(0)\|_{L^2(\Omega)}\end{aligned}$$

Proof idea : Test equations with  $q_h = p_h(t)$  and  $v_h = u_h(t)$ .



## Motivation for new method

$$\begin{aligned}(\partial_t u_h(t), v_h) - (p_h(t), \operatorname{div} v_h) &= (f(t), v_h) & \forall v_h \in V_h, \\(\partial_t p_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= (g(t), q_h) & \forall q_h \in Q_h.\end{aligned}$$

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$$\|\rho_h u(t) - u_h(t)\|_{L^2(\Omega)} + \|\pi_h^0 p(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u, p) h^2$$

For  $w_h(t) = \rho_h u(t) - u_h(t)$  and  $r_h(t) = \pi_h^0 p(t) - p_h(t)$ , we have

$$\begin{aligned}(\partial_t w_h(t), v_h) - (r_h(t), \operatorname{div} v_h) &= (\tilde{f}(t), v_h) \\(\partial_t r_h(t), q_h) + (\operatorname{div} w_h(t), q_h) &= (\tilde{g}(t), q_h)\end{aligned}$$

with initial values  $w_h(0) = 0$ ,  $r_h(0) = 0$  and right hand sides

$$\begin{aligned}(\tilde{f}(t), v_h) &= (\partial_t(\rho_h u(t) - u(t)), v_h) + (\pi_h^0 p(t) - p(t), \operatorname{div} v_h) \\(\tilde{g}(t), q_h) &= (\partial_t(\pi_h^0 p(t) - p(t)), q_h) + (\operatorname{div} \rho_h u(t) - \operatorname{div} u(t), q_h) = 0\end{aligned}$$

## Motivation for new method

$$\begin{aligned}(\partial_t u_h(t), v_h) - (p_h(t), \operatorname{div} v_h) &= 0 \quad \forall v_h \in V_h, \\(\partial_t p_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 \quad \forall q_h \in Q_h.\end{aligned}$$

### Theorem (Error estimate for the semi-discretization)

$$\|\rho_h u(t) - u_h(t)\|_{L^2(\Omega)} + \|\pi_h^0 p(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u, p) h^2$$

For  $w_h(t) = \rho_h u(t) - u_h(t)$  and  $r_h(t) = \pi_h^0 p(t) - p_h(t)$ , we have

$$\begin{aligned}(\partial_t w_h(t), v_h) - (r_h(t), \operatorname{div} v_h) &= (\tilde{f}(t), v_h) \\(\partial_t r_h(t), q_h) + (\operatorname{div} w_h(t), q_h) &= (\tilde{g}(t), q_h)\end{aligned}$$

with initial values  $w_h(0) = 0$ ,  $r_h(0) = 0$  and right hand sides

$$\begin{aligned}(\tilde{f}(t), v_h) &\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} \\(\tilde{g}(t), q_h) &= 0\end{aligned}$$

## Motivation for new method

$$\begin{aligned}(\partial_t u_h(t), v_h)_h - (\rho_h(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h, \\(\partial_t \rho_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 & \forall q_h \in Q_h.\end{aligned}$$

### Theorem (Error estimate for the semi-discretization)

$$\|\rho_h u(t) - u_h(t)\|_{L^2(\Omega)} + \|\pi_h^0 \rho(t) - \rho_h(t)\|_{L^2(\Omega)} \leq \dots$$

For  $w_h(t) = \rho_h u(t) - u_h(t)$  and  $r_h(t) = \pi_h^0 \rho(t) - \rho_h(t)$ , we have

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with initial values  $w_h(0) = 0$ ,  $r_h(0) = 0$  and right hand sides

$$\begin{aligned}(\tilde{f}(t), v_h) &\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + (\rho_h \partial_t u(t), v_h) - (\rho_h \partial_t u(t), v_h)_h \\&\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + Ch \|\partial_t u(t)\|_{H^1(\Omega)} \|v_h\|_{L^2(\Omega)} \\(\tilde{g}(t), q_h) &= 0\end{aligned}$$

## Motivation for new method

$$\begin{aligned}(\partial_t u_h(t), v_h)_h - (\rho_h(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h, \\(\partial_t \rho_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 & \forall q_h \in Q_h.\end{aligned}$$

### Theorem (Error estimate for the semi-discretization)

$$\|\rho_h u(t) - u_h(t)\|_{L^2(\Omega)} + \|\pi_h^0 \rho(t) - \rho_h(t)\|_{L^2(\Omega)} \leq C(u, \rho)h$$

For  $w_h(t) = \rho_h u(t) - u_h(t)$  and  $r_h(t) = \pi_h^0 \rho(t) - \rho_h(t)$ , we have

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with initial values  $w_h(0) = 0$ ,  $r_h(0) = 0$  and right hand sides

$$\begin{aligned}(\tilde{f}(t), v_h) &\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + (\rho_h \partial_t u(t), v_h) - (\rho_h \partial_t u(t), v_h)_h \\&\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + Ch \|\partial_t u(t)\|_{H^1(\Omega)} \|v_h\|_{L^2(\Omega)} \\(\tilde{g}(t), q_h) &= 0\end{aligned}$$

## Taking a step back ...

Consider the elliptic projection

$$\begin{aligned}(w_h, v_h) - (r_h, \operatorname{div} v_h) &= (w, v_h) - (r, \operatorname{div} v_h) && \forall v_h \in V_h, \\ (\operatorname{div} w_h, q_h) &= (\operatorname{div} w, q_h) && \forall q_h \in Q_h.\end{aligned}$$



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Consider the elliptic projection

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## Taking a step back ...

Consider the elliptic projection

$$\begin{aligned}(\mathbf{w}_h, \mathbf{v}_h)_h - (r_h, \operatorname{div} \mathbf{v}_h) &= (\mathbf{w}, \mathbf{v}_h) - (r, \operatorname{div} \mathbf{v}_h) & \forall \mathbf{v}_h \in V_h, \\ (\operatorname{div} \mathbf{w}_h, \mathbf{q}_h) &= (\operatorname{div} \mathbf{w}, \mathbf{q}_h) & \forall \mathbf{q}_h \in Q_h.\end{aligned}$$

### Lemma (Estimates for the elliptic projection)

If  $\Omega$  is convex, we have

$$\|\pi_h^0 r - r_h\|_{L^2(\Omega)} \leq Ch^2 (\|\mathbf{w}\|_{H^1(\Omega)} + \|\operatorname{div} \mathbf{w}\|_{H^1(\Omega)}).$$

whenever  $w$  and  $r$  are sufficiently smooth.

Vague idea : Duality arguments and

$$|(u_h, \mathbf{v}_h) - (u_h, \mathbf{v}_h)_h| \leq \begin{cases} Ch \|u_h\|_{H^1(\Omega)} \|\mathbf{v}_h\|_{L^2(\Omega)} \\ Ch^2 \|u_h\|_{H^1(\Omega)} \|\mathbf{v}_h\|_{H^1(\Omega)} \end{cases}$$



M. Wheeler and I. Yotov.

A multipoint flux mixed finite element method.

*SIAM J. Numer. Anal.*, Vol. 44, No. 5, pp. 2082–2106.

## Auxiliary functions

Consider the functions  $u_h^* \in C^1(0, T; V_h)$  and  $p_h^* \in C(0, T; Q_h)$  satisfying

$$\begin{aligned}(\partial_t u_h^*(t), v_h)_h - (p_h^*(t), \operatorname{div} v_h) &= (\partial_t u(t), v_h) - (p(t), \operatorname{div} v_h) && \forall v_h \in V_h \\(\operatorname{div} \partial_t u_h^*(t), q_h) &= (\operatorname{div} \partial_t u(t), q_h) && \forall q_h \in Q_h\end{aligned}$$

## Auxiliary functions

Consider the functions  $u_h^* \in C^1(0, T; V_h)$  and  $p_h^* \in C(0, T; Q_h)$  satisfying

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and

$$\begin{aligned}(u_h^*(0), v_h)_h - (r_h^*(0), \operatorname{div} v_h) &= (u(0), v_h) & \forall v_h \in V_h \\(\operatorname{div} u_h^*(0), q_h) &= (\operatorname{div} u(0), q_h) & \forall q_h \in Q_h\end{aligned}$$

### Lemma (Approximation error estimates)

We have

$$(\operatorname{div} u_h^*(t) - \operatorname{div} u(t), q_h) = 0, \quad \forall q_h \in Q_h$$

Moreover, if  $\Omega$  is convex, we have

$$\|\pi_h^0 p(t) - p_h^*(t)\|_{L^2(\Omega)} \leq Ch^2 (\|\partial_t u(t)\|_{H^1(\Omega)} + \|\operatorname{div} \partial_t u(t)\|_{H^1(\Omega)})$$

whenever  $u$  is sufficiently smooth.

## Motivation for new method

$$\begin{aligned}(\partial_t u_h(t), v_h)_h - (\rho_h(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h, \\(\partial_t \rho_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 & \forall q_h \in Q_h.\end{aligned}$$

### Theorem (Error estimate for the semi-discretization)

$$\|\rho_h u(t) - u_h(t)\|_{L^2(\Omega)} + \|\pi_h^0 \rho(t) - \rho_h(t)\|_{L^2(\Omega)} \leq C(u, \rho)h$$

For  $w_h(t) = \rho_h u(t) - u_h(t)$  and  $r_h(t) = \pi_h^0 \rho(t) - \rho_h(t)$ , we have

$$\begin{aligned}(\partial_t w_h(t), v_h)_h - (r_h(t), \operatorname{div} v_h) &= (\tilde{f}(t), v_h) \\(\partial_t r_h(t), q_h) + (\operatorname{div} w_h(t), q_h) &= (\tilde{g}(t), q_h)\end{aligned}$$

with initial values  $w_h(0) = 0$ ,  $r_h(0) = 0$  and right hand sides

$$\begin{aligned}(\tilde{f}(t), v_h) &\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + (\rho_h \partial_t u(t), v_h) - (\rho_h \partial_t u(t), v_h)_h \\&\leq Ch^2 \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} + Ch \|\partial_t u(t)\|_{H^2(\Omega)} \|v_h\|_{L^2(\Omega)} \\(\tilde{g}(t), q_h) &= 0\end{aligned}$$

## A new method

$$\begin{aligned}(\partial_t u_h(t), v_h)_h - (p_h(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h, \\(\partial_t p_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 & \forall q_h \in Q_h.\end{aligned}$$

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$$\begin{aligned}(\tilde{f}(t), v_h) &= (\partial_t u_h^*(t), v_h)_h - (p_h^*(t), \operatorname{div} v_h) = 0 \\(\tilde{g}(t), q_h) &= (\partial_t p_h^*(t) - \partial_t p(t), q_h) + (\operatorname{div} u_h^*(t) - \operatorname{div} u(t), q_h) \\&\leq \|\partial_t p_h^*(t) - \partial_t \pi_h^0 p(t)\|_{L^2(\Omega)} \|q_h\|_{L^2(\Omega)}\end{aligned}$$

## A new method

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### Theorem (Error estimate for the semi-discretization)

$$\|u_h^*(t) - u_h(t)\|_{L^2(\Omega)} + \|p_h^*(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u)h^2$$

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## A new method

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Theorem (Error estimate for the semi-discretization)

$$\|\pi_h^0 p(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u) h^2$$

Proof: Split  $\|\pi_h^0 p(t) - p_h(t)\| \leq \|\pi_h^0 p(t) - p_h^*(t)\| + \|p_h^*(t) - p_h(t)\|$ .

## A new method

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What is  $C(u)$  ? One of the terms it contains is

$$\|\operatorname{div} \partial_{tt} u(t)\|_{H^1(\Omega)}$$

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$$\|\operatorname{div} \partial_{tt} u(t)\|_{H^1(\Omega)}$$

$$\|\pi_h^0 \partial_t p(t) - \partial_t p_h^*(t)\|_{L^2(\Omega)} \leq Ch^2 (\|\partial_t \partial_{tt} u(t)\|_{H^1(\Omega)} + \|\operatorname{div} \partial_t \partial_{tt} u(t)\|_{H^1(\Omega)})$$

## Post-processing for the pressure

Idea : Construct  $\tilde{p}_h \in P_1(\mathcal{T}_h)$  from  $u_h, p_h$ . Testing the momentum equation with  $\nabla q \in L^2(\Omega)^2$  gives

$$(\nabla p, \nabla q)_K = -(\partial_t u, \nabla q)_K.$$

## Post-processing for the pressure

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$$(\nabla p, \nabla q)_K = -(\partial_t u, \nabla q)_K.$$

### Problem

For all  $K \in \mathcal{T}_h$ ,  $t > 0$  find  $\tilde{p}_h(t) \in P_1(K)$  such that

$$\begin{aligned}(\nabla \tilde{p}_h(t), \nabla \tilde{q}_h)_K &= -(\partial_t u_h(t), \nabla \tilde{q}_h)_K & \forall \tilde{q}_h \in P_1(K) \\(\tilde{p}_h(t), q_h)_K &= (p_h(t), q_h)_K & \forall q_h \in P_0(K),\end{aligned}$$



R. Stenberg *Postprocessing schemes for some mixed finite elements.* RAIRO Model. Math. Anal. Numer. 1991



Y. Chen *Global superconvergence for a mixed finite element method for the wave equation.* Systems Sci. Math. Sci. 1999

## Post-Processing for the pressure

### Theorem

*For  $(p, u)$  sufficiently smooth, we have*

$$\|p(t) - \tilde{p}_h(t)\|_{L^2(\Omega)} \leq C(p, u)h^2$$

## Post-Processing for the pressure

### Theorem

For  $(p, u)$  sufficiently smooth, we have

$$\|p(t) - \tilde{p}_h(t)\|_{L^2(\Omega)} \leq C(p, u)h^2$$

We split the error

$$\begin{aligned} \|p - \tilde{p}_h\|_{L^2(K)} &\leq \|p - \pi_1 p\|_{L^2(K)} + \|\pi_0(\pi_1 p - \tilde{p}_h)\|_{L^2(K)} + \|(\text{Id} - \pi_0)(\pi_1 p - \tilde{p}_h)\|_{L^2(K)} \\ &\leq \|p - \pi_1 p\|_{L^2(K)} + \|\pi_0 p - p_h\|_{L^2(K)} + h_K \|\nabla(\pi_1 p - \tilde{p}_h)\|_{L^2(K)}. \end{aligned}$$



## Post-Processing for the pressure

### Theorem

For  $(p, u)$  sufficiently smooth, we have

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We compute

$$\begin{aligned} (\nabla(\pi_1 p - \tilde{p}_h), \nabla \tilde{q}_h)_K &= (\nabla(\pi_1 p - p), \nabla \tilde{q}_h)_K + (\nabla(p - \tilde{p}_h), \nabla \tilde{q}_h)_K \\ &= (\nabla(\pi_1 p - p), \nabla \tilde{q}_h)_K - (\partial_t(u - u_h), \nabla \tilde{q}_h)_K \\ &\leq (\|\nabla(\pi_1 p - p)\|_{L^2(K)} + \|\partial_t(u - u_h)\|_{L^2(K)}) \|\nabla \tilde{q}_h\|_{L^2(K)}. \end{aligned}$$

## Auxiliary functions

Consider the functions  $u_h^* \in C^1(0, T; V_h)$  and  $p_h^* \in C(0, T; Q_h)$  satisfying

$$\begin{aligned}(\partial_t u_h^*(t), v_h)_h - (p_h^*(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h \\(\operatorname{div} \partial_t u_h^*(t), q_h) &= (\operatorname{div} \partial_t u(t), q_h) & \forall q_h \in Q_h\end{aligned}$$

and

$$\begin{aligned}(u_h^*(0), v_h)_h - (r_h^*(0), \operatorname{div} v_h) &= (u(0), v_h) & \forall v_h \in V_h \\(\operatorname{div} u_h^*(0), q_h) &= (\operatorname{div} u(0), q_h) & \forall q_h \in Q_h\end{aligned}$$

### Lemma (Approximation error estimates)

We have

$$(\operatorname{div} u_h^*(t) - \operatorname{div} u(t), q_h) = 0, \quad \forall q_h \in Q_h$$

Moreover, if  $\Omega$  is convex, we have

$$\|\pi_h^0 p(t) - p_h^*(t)\|_{L^2(\Omega)} \leq Ch^2 (\|\partial_t u(t)\|_{H^1(\Omega)} + \|\operatorname{div} \partial_t u(t)\|_{H^1(\Omega)})$$

whenever  $u$  is sufficiently smooth.

## Auxiliary functions

Consider the functions  $\tilde{u}_h^* \in C^1(0, T; V_h)$  and  $\tilde{p}_h^* \in C(0, T; Q_h)$  satisfying

$$\begin{aligned}(\partial_t \tilde{u}_h^*(t), v_h) - (\tilde{p}_h^*(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h \\(\operatorname{div} \partial_t \tilde{u}_h^*(t), q_h) &= (\operatorname{div} \partial_t u(t), q_h) & \forall q_h \in Q_h\end{aligned}$$

and

$$\begin{aligned}(\tilde{u}_h^*(0), v_h) - (\tilde{r}_h^*(0), \operatorname{div} v_h) &= (u(0), v_h) & \forall v_h \in V_h \\(\operatorname{div} \tilde{u}_h^*(0), q_h) &= (\operatorname{div} u(0), q_h) & \forall q_h \in Q_h\end{aligned}$$

### Lemma (Approximation error estimates)

We have

$$(\operatorname{div} \tilde{u}_h^*(t) - \operatorname{div} u(t), q_h) = 0, \quad \forall q_h \in Q_h$$

Moreover, we get

$$\|u(t) - \tilde{u}_h^*(t)\| \leq C(u)h^2$$

whenever  $u$  is sufficiently smooth.

## Post-processing for the velocity

First try :

$$(\tilde{u}_h(t), v_h) = (u_h(t), v_h)_h \quad \forall v_h \in V_h$$

$$\|u(t) - \tilde{u}_h(t)\|_{L^2} \leq \overbrace{\|u(t) - \pi_1^0 u(t)\|_{L^2}}^{O(h^2)} + \overbrace{\|\pi_1^0 u(t) - \tilde{u}_h(t)\|_{L^2}}^{O(h^{3/2})} \leq C(u)h^{3/2} \quad ?$$

## Post-processing for the velocity

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$$\|u(t) - \tilde{u}_h(t)\|_{L^2} \leq \overbrace{\|u(t) - \pi_1^0 u(t)\|_{L^2}}^{O(h^2)} + \overbrace{\|\pi_1^0 u(t) - \tilde{u}_h(t)\|_{L^2}}^{O(h^{3/2})} \leq C(u)h^{3/2} \quad ?$$

Second try :

$$\begin{aligned} (\tilde{u}_h(t), v_h) - (\tilde{r}_h(t), \operatorname{div} v_h) &= (u_h(t), v_h)_h & \forall v_h \in V_h, \\ (\operatorname{div} \tilde{u}_h(t), q_h) &= (\operatorname{div} u_h(t), q_h) & \forall q_h \in Q_h. \end{aligned}$$

$$\|u(t) - \tilde{u}_h(t)\|_{L^2} \leq \overbrace{\|u(t) - \pi_1^0 u(t)\|_{L^2}}^{O(h^2)} + \overbrace{\|\pi_1^0 u(t) - \tilde{u}_h(t)\|_{L^2}}^{O(h^2)} \leq C(u)h^2$$

## Post-processing for the velocity

### Problem (Post-processing strategy for the velocity)

For every  $0 \leq t \leq T$ , find  $\tilde{u}_h(t) \in V_h$  such that

$$\begin{aligned}(\tilde{u}_h(t), v_h) - (\tilde{r}_h(t), \operatorname{div} v_h) &= (u_h(t), v_h)_h & \forall v_h \in V_h, \\(\operatorname{div} \tilde{u}_h(t), q_h) &= (\operatorname{div} u_h(t), q_h) & \forall q_h \in Q_h.\end{aligned}$$

## Post-processing for the velocity

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For every  $0 \leq t \leq T$ , find  $\tilde{u}_h(t) \in V_h$  such that

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### Theorem (Error estimate for the improved velocity)

Let  $\Omega$  be convex. Then

$$\|u(t) - \tilde{u}_h(t)\|_{L^2(\Omega)} \leq C(u)h^2$$

## Post-processing for the velocity

Proof:

Post-processing scheme at  $t = 0$

$$\begin{aligned}(\tilde{u}_h(0), v_h) - (\tilde{r}_h(0), \operatorname{div} v_h) &= (u_h(0), v_h)_h & \forall v_h \in V_h, \\(\operatorname{div} \tilde{u}_h(0), q_h) &= (\operatorname{div} u_h(0), q_h) & \forall q_h \in Q_h.\end{aligned}$$

Exact elliptic projection for the initial conditions

$$\begin{aligned}(\tilde{u}_h^*(0), v_h) - (\tilde{r}_h^*(0), \operatorname{div} v_h) &= (u(0), v_h) & \forall v_h \in V_h \\(\operatorname{div} \tilde{u}_h^*(0), q_h) &= (\operatorname{div} u(0), q_h) & \forall q_h \in Q_h\end{aligned}$$

Inexact elliptic projection for the initial conditions

$$\begin{aligned}(u_h^*(0), v_h)_h - (r_h^*(0), \operatorname{div} v_h) &= (u(0), v_h) & \forall v_h \in V_h \\(\operatorname{div} u_h^*(0), q_h) &= (\operatorname{div} u(0), q_h) & \forall q_h \in Q_h\end{aligned}$$



## Post-processing for the velocity

Proof:

$$(i) = (\tilde{u}_h(0), v_h) - (\tilde{r}_h(0), \operatorname{div} v_h) = (u_h(0), v_h)_h$$

$$(ii) = (\tilde{u}_h^*(0), v_h) - (\tilde{r}_h^*(0), \operatorname{div} v_h) = (u(0), v_h)$$

$$(iii) = (u_h^*(0), v_h)_h - (r_h^*(0), \operatorname{div} v_h) = (u(0), v_h)$$

Computing  $(ii) - (i) - (iii)$  and using  $u_h(0) = u_h^*(0)$  yields

$$(\tilde{u}_h^*(0) - \tilde{u}_h(0), v_h) = (\tilde{r}_h^*(0) - \tilde{r}_h(0) - r_h^*(0), \operatorname{div} v_h)$$

This means

$$(\tilde{u}_h^*(0) - \tilde{u}_h(0), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

## Post-processing for the velocity

Proof:

$$(\tilde{u}_h^*(0) - \tilde{u}_h(0), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

Post-processing scheme

$$\begin{aligned}(\partial_t \tilde{u}_h(t), v_h) - (\partial_t \tilde{r}_h(t), \operatorname{div} v_h) &= (\partial_t u_h(t), v_h)_h & \forall v_h \in V_h \\(\operatorname{div} \partial_t \tilde{u}_h(t), q_h) &= (\operatorname{div} \partial_t u_h(t), q_h) & \forall q_h \in Q_h\end{aligned}$$

Exact elliptic projection

$$\begin{aligned}(\partial_t \tilde{u}_h^*(t), v_h) - (\tilde{p}_h^*(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h \\(\operatorname{div} \partial_t \tilde{u}_h^*(t), q_h) &= (\operatorname{div} \partial_t u(t), q_h) & \forall q_h \in Q_h\end{aligned}$$

Inexact elliptic projection

$$\begin{aligned}(\partial_t u_h^*(t), v_h)_h - (p_h^*(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h \\(\operatorname{div} \partial_t u_h^*(t), q_h) &= (\operatorname{div} \partial_t u(t), q_h) & \forall q_h \in Q_h\end{aligned}$$

## Post-processing for the velocity

Proof:

$$(\tilde{u}_h^*(0) - \tilde{u}_h(0), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

$$(i) = (\partial_t \tilde{u}_h(t), v_h) - (\partial_t \tilde{r}_h(t), \operatorname{div} v_h) = (\partial_t u_h(t), v_h)_h$$

$$(ii) = (\partial_t \tilde{u}_h^*(t), v_h) - (\tilde{p}_h^*(t), \operatorname{div} v_h) = 0$$

$$(iii) = (\partial_t u_h^*(t), v_h)_h - (p_h^*(t), \operatorname{div} v_h) = 0$$

Computing  $(ii) - (i) - (iii)$  and using  $\partial_t u_h(0) = \partial_t u_h^*(0)$  yields

$$(\partial_t \tilde{u}_h^*(t) - \partial_t \tilde{u}_h(t), v_h) = (\tilde{p}_h^*(t) - p_h(t) - \partial_t \tilde{r}_h(t), \operatorname{div} v_h)$$

This means

$$(\partial_t \tilde{u}_h^*(t) - \partial_t \tilde{u}_h(t), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

## Post-processing for the velocity

Proof:

$$\begin{aligned}(\tilde{u}_h^*(0) - \tilde{u}_h(0), v_h) &= 0 & \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0 \\(\partial_t \tilde{u}_h^*(t) - \partial_t \tilde{u}_h(t), v_h) &= 0 & \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0\end{aligned}$$

## Post-processing for the velocity

Proof:

$$(\tilde{u}_h^*(t) - \tilde{u}_h(t), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

## Post-processing for the velocity

Proof:

$$(\tilde{u}_h^*(t) - \tilde{u}_h(t), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

Divergence condition of the post-processing scheme

$$(\operatorname{div} \tilde{u}_h(t), q_h) = (\operatorname{div} u_h(t), q_h) \quad \forall q_h \in Q_h$$

Property of the inexact elliptic projection

$$(\operatorname{div} \tilde{u}_h^*(t), q_h) = (\operatorname{div} u(t), q_h) \quad \forall q_h \in Q_h$$

Property of the exact elliptic projection

$$(\operatorname{div} u_h^*(t), q_h) = (\operatorname{div} u(t), q_h) \quad \forall q_h \in Q_h$$

## Post-processing for the velocity

Proof:

$$(\tilde{u}_h^*(t) - \tilde{u}_h(t), v_h) = 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0$$

Divergence condition of the post-processing scheme

$$(i) = (\operatorname{div} \tilde{u}_h(t), q_h) = (\operatorname{div} u_h(t), q_h)$$

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$$(iii) = (\operatorname{div} u_h^*(t), q_h) = (\operatorname{div} u(t), q_h)$$

Computing  $(ii) - (i) - (iii)$  yields

$$(\operatorname{div} (\tilde{u}_h^*(t) - \tilde{u}_h(t) + u_h(t) - u_h^*(t)), q_h) = 0 \quad \forall q_h \in Q_h$$

## Post-processing for the velocity

Proof:

$$\begin{aligned}(\tilde{u}_h^*(t) - \tilde{u}_h(t), v_h) &= 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0 \\(\operatorname{div}(\tilde{u}_h^*(t) - \tilde{u}_h(t)) + u_h(t) - u_h^*(t)), q_h &= 0 \quad \forall q_h \in Q_h\end{aligned}$$



## Post-processing for the velocity

Proof:

$$\begin{aligned}(\tilde{u}_h^*(t) - \tilde{u}_h(t), v_h) &= 0 \quad \forall v_h \in V_h \text{ with } \operatorname{div} v_h = 0 \\(\operatorname{div}(\tilde{u}_h^*(t) - \tilde{u}_h(t)) + u_h(t) - u_h^*(t), q_h) &= 0 \quad \forall q_h \in Q_h\end{aligned}$$

Actual start of the proof:

$$\|u(t) - \tilde{u}_h(t)\|_{L^2(\Omega)} \leq \|u(t) - \tilde{u}_h^*(t)\|_{L^2(\Omega)} + \|\tilde{u}_h^*(t) - \tilde{u}_h(t)\|_{L^2(\Omega)}$$

We have  $\|u(t) - \tilde{u}_h^*(t)\|_{L^2(\Omega)} \leq C(u)h^2$ . For the second term, we compute

$$\begin{aligned}\|\tilde{u}_h^*(t) - \tilde{u}_h(t)\|_{L^2(\Omega)}^2 &= (\tilde{u}_h^*(t) - \tilde{u}_h(t), \tilde{u}_h^*(t) - \tilde{u}_h(t) + u_h(t) - u_h^*(t))_{\Omega} \\&\quad + (\tilde{u}_h^*(t) - \tilde{u}_h(t), u_h^*(t) - u_h(t))_{\Omega} \\&\leq \|\tilde{u}_h^*(t) - \tilde{u}_h(t)\|_{L^2(\Omega)} \|u_h^*(t) - u_h(t)\|_{L^2(\Omega)}\end{aligned}$$

In summary, we get

$$\|\tilde{u}_h^*(t) - \tilde{u}_h(t)\|_{L^2(\Omega)} \leq \|u_h^*(t) - u_h(t)\|_{L^2(\Omega)} \leq C(u)h^2$$

# Post-processing

## Problem

For  $(u_h(0), p_h(0)) = (\rho_h u_0, \pi_h^0 p_0)$  and all  $t > 0$  find  $(u_h(t), p_h(t)) \in V_h \times Q_h$  such that

$$\begin{aligned}(\partial_t u_h(t), v_h)_h - (p_h(t), \operatorname{div} v_h) &= 0 & \forall v_h \in V_h, \\(\partial_t p_h(t), q_h) + (\operatorname{div} u_h(t), q_h) &= 0 & \forall q_h \in Q_h.\end{aligned}$$

## Theorem (Error estimate for the semi-discretization)

Let  $V_h = BDM_1$ ,  $Q_h = P_0$ . Then if  $(u, p)$  sufficiently smooth

$$\|u(t) - u_h(t)\|_{L^2(\Omega)} + \|p(t) - p_h(t)\|_{L^2(\Omega)} \leq C(u, p)h.$$

## Theorem (Full post-processing error)

Let  $V_h = BDM_1$ ,  $Q_h = P_0$ . Then if  $(u, p)$  sufficiently smooth

$$\|u(t) - \tilde{u}_h(t)\|_{L^2(\Omega)} + \|p(t) - \tilde{p}_h(t)\|_{L^2(\Omega)} \leq C(u, p)h^2.$$

# The fully discrete scheme

## Problem (Fully discrete problem)

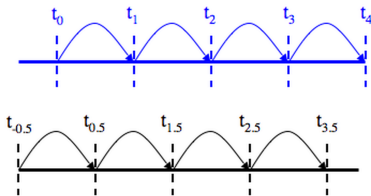
Set  $u_h^0 = u_h^*(0)$  and  $p_h^0 = p_h^*(0)$  and define  $u_h^{-1/2} \in V_h$  as solution of

$$(u_h^{-1/2}, v_h)_h = (u_h^0, v_h)_h - \frac{\tau}{2}(p_h^0, \operatorname{div} v_h) \quad \forall v_h \in V_h. \quad (1)$$

Then for  $n \geq 0$  find  $(u_h^{n+1/2}, p_h^{n+1}) \in V_h \times Q_h$ , such that

$$\left( \frac{u_h^{n+1/2} - u_h^{n-1/2}}{\tau}, v_h \right)_h - (p_h^n, \operatorname{div} v_h) = 0 \quad \forall v_h \in V_h. \quad (2)$$

$$\left( \frac{p_h^{n+1} - p_h^n}{\tau}, q_h \right) + (\operatorname{div} u_h^{n+1/2}, q_h) = 0 \quad \forall q_h \in Q_h. \quad (3)$$



# Fully discrete results

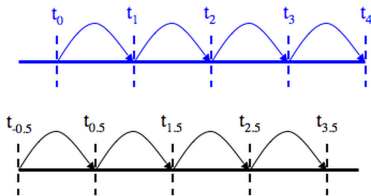
## Theorem (Estimates for the discrete error)

Let  $\Omega$  be convex. Then, if the CFL condition is satisfied

$$\|\hat{u}_h^n - \hat{u}_h^*(t^n)\|_{L^2(\Omega)} + \|p_h^n - \hat{p}_h^*(t^n)\|_{L^2(\Omega)} \leq C(u)(h^2 + \tau^2)$$

for all  $0 \leq n \leq N - 1$ . In addition, we also have

$$\|p_h^n - \pi_h^0 p(t^n)\|_{L^2(\Omega)} \leq C(u)(h^2 + \tau^2).$$



## Fully discrete results

### Theorem (Estimates for the discrete error)

Let  $\Omega$  be convex. Then, if the CFL condition is satisfied

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$$\|p_h^n - \pi_h^0 p(t^n)\|_{L^2(\Omega)} \leq C(u)(h^2 + \tau^2).$$

### Theorem (Post-processing error)

Let  $V_h = BDM_1$ ,  $Q_h = P_0$ . Then if  $(u, p)$  sufficiently smooth

$$\|u(t^n) - \widetilde{u}_h^n\|_{L^2(\Omega)} + \|p(t^n) - \widetilde{p}_h^n\|_{L^2(\Omega)} \leq C(u, p)(h^2 + \tau^2).$$

## Remarks

- ▶ Extension to the a fully discrete scheme
- ▶ Only for lowest order  $Q_h = P_0$  and  $V_h = BDM_1$
- ▶ The convexity condition is sufficient.
- ▶ We require quasi-uniformity of the triangulation  $\mathcal{T}_h$ .
- ▶ Can compete with FDTD, does not require uniform grid.

## Numerical results

Let  $\Omega = (-1, 1)^2$  and take

$$p(x, y, t) = \sin(\pi x) \sin(\pi y) \left( \sin(\pi t \sqrt{2}) + \cos(\pi t \sqrt{2}) \right)$$

$$u(x, y, t) = -\frac{\sqrt{2}}{2} \left( \sin(\pi t \sqrt{2}) - \cos(\pi t \sqrt{2}) \right) \begin{pmatrix} \cos(\pi x) \sin(\pi y) \\ \sin(\pi x) \cos(\pi y) \end{pmatrix}$$

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$(\cdot, \cdot)$	$p_h^0 = \pi_h^0 p(0)$ $u_h^0 = \rho_h u(0)$
$\ u_h^n - u(t^n)\ _{L^2(\Omega)} + \ p_h^n - p(t^n)\ _{L^2(\Omega)}$	$O(h)$
$\ u_h^n - \rho_h u(t^n)\ _{L^2(\Omega)} + \ p_h^n - \pi_h^0 p(t^n)\ _{L^2(\Omega)}$	$O(h^2)$
$\ p(t^n) - \tilde{p}_h^n\ _{L^2(\Omega)}$	$O(h^2)$



# Numerical results

$(\cdot, \cdot)_h$	$p_h^0 = p_h^*(0)$ $u_h^0 = u_h^*(0)$	$p_h^0 = \pi_h^0 p(0)$ $u_h^0 = \rho_h u(0)$
$\ u_h^n - u(t^n)\ _{L^2(\Omega)} + \ p_h^n - p(t^n)\ _{L^2(\Omega)}$	$O(h)$	$O(h)$
$\ u_h^n - u_h^*(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$
$\ p_h^n - \pi_h^0 p(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h^2) ?$
$\ u_h^n - u_h^*(t^n)\ _{L^2(\Omega)} + \ p_h^n - p_h^*(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$
$\ p(t^n) - \tilde{p}_h^n\ _{L^2(\Omega)}$	$O(h^2)$	$O(h^2) ?$
$\ u(t^n) - \tilde{u}_h^n\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$

## Numerical results

$(\cdot, \cdot)_h$	$p_h^0 = p_h^*(0)$ $u_h^0 = u_h^*(0)$	$p_h^0 = \pi_h^0 p(0)$ $u_h^0 = \rho_h u(0)$
$\ u_h^n - u(t^n)\ _{L^2(\Omega)} + \ p_h^n - p(t^n)\ _{L^2(\Omega)}$	$O(h)$	$O(h)$
$\ u_h^n - u_h^*(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$
$\ p_h^n - \pi_h^0 p(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h^2) ?$
$\ u_h^n - u_h^*(t^n)\ _{L^2(\Omega)} + \ p_h^n - p_h^*(t^n)\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$
$\ p(t^n) - \tilde{p}_h^n\ _{L^2(\Omega)}$	$O(h^2)$	$O(h^2) ?$
$\ u(t^n) - \tilde{u}_h^n\ _{L^2(\Omega)}$	$O(h^2)$	$O(h)$

Thank you for your attention

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